

## WASSP data processing in Echoview

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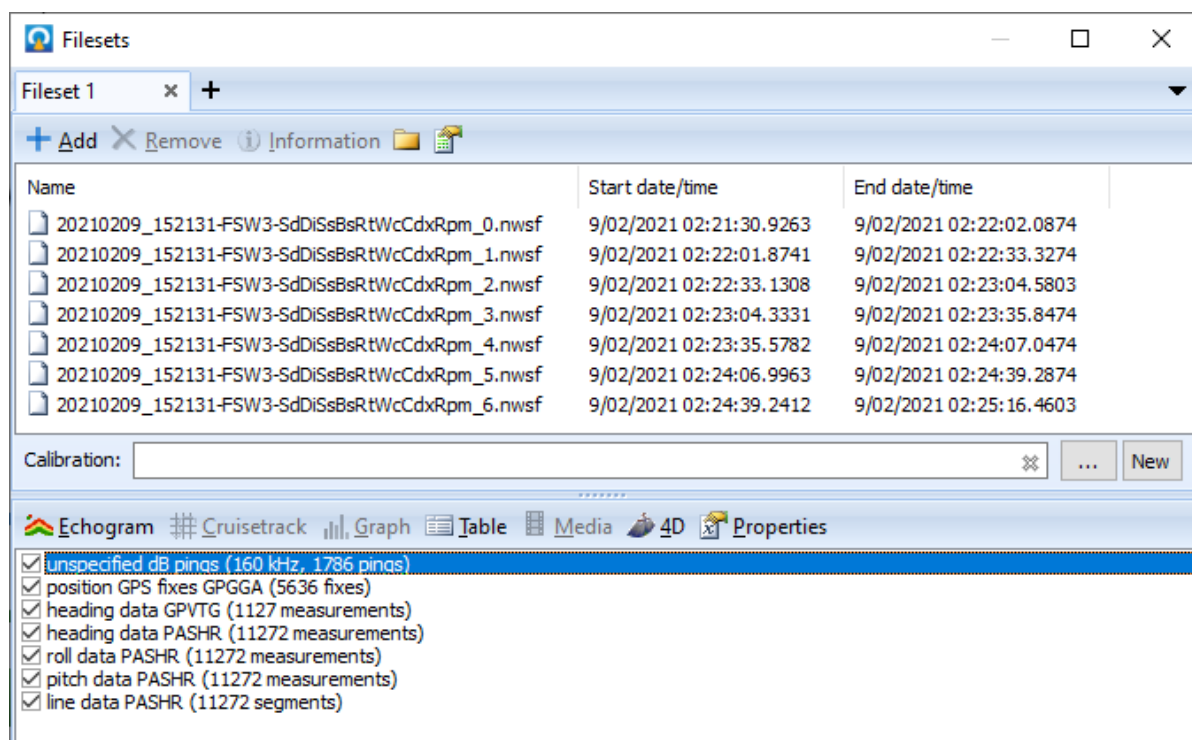
Echoview can load and analyze WASSP data files stored in the \*.nwsf format.

Echoview version 6.1 or newer must be used for WASSP compatibility - however we recommend using the very latest version available for the best performance and the widest range of features that can be used in WASSP data processing, which is Echoview 12 at the time of writing. All of the features described below are available in Echoview 12, but some are not available in older versions. Future versions of Echoview are likely to have even more features that are relevant to WASSP data processing.

Initially, Echoview's compatibility was with the WMB-3250 model only, but in more recent times WASSP have provided an option for other models to convert data to this same format. File export to \*.nwsf requires the purchase of a software license option from WASSP.

For WASSP data files, Echoview will derive:

- **Unspecified dB multibeam pings**
  - This is uncalibrated backscatter, but dB offsets can optionally be applied to individual beams and/or all samples in Echoview, if corrections have been calculated by the user.
- **GPS, heading, pitch, roll, and depth** measurements that are recorded to file, if available.



The screenshot shows the 'Filesets' window in Echoview. It displays a list of files under 'Fileset 1'. The files are named with a date and time, followed by a file extension. Below the file list, there is a 'Calibration' field and a 'New' button. At the bottom, there is a list of variables derived from the files, with checkboxes next to each variable.

| Name   | Start date/time         | End date/time           |
|--|-------------------------|-------------------------|
| 20210209_152131-FSW3-SdDiSsBsRtWcCdxRpm_0.nwsf | 9/02/2021 02:21:30.9263 | 9/02/2021 02:22:02.0874 |
| 20210209_152131-FSW3-SdDiSsBsRtWcCdxRpm_1.nwsf | 9/02/2021 02:22:01.8741 | 9/02/2021 02:22:33.3274 |
| 20210209_152131-FSW3-SdDiSsBsRtWcCdxRpm_2.nwsf | 9/02/2021 02:22:33.1308 | 9/02/2021 02:23:04.5803 |
| 20210209_152131-FSW3-SdDiSsBsRtWcCdxRpm_3.nwsf | 9/02/2021 02:23:04.3331 | 9/02/2021 02:23:35.8474 |
| 20210209_152131-FSW3-SdDiSsBsRtWcCdxRpm_4.nwsf | 9/02/2021 02:23:35.5782 | 9/02/2021 02:24:07.0474 |
| 20210209_152131-FSW3-SdDiSsBsRtWcCdxRpm_5.nwsf | 9/02/2021 02:24:06.9963 | 9/02/2021 02:24:39.2874 |
| 20210209_152131-FSW3-SdDiSsBsRtWcCdxRpm_6.nwsf | 9/02/2021 02:24:39.2412 | 9/02/2021 02:25:16.4603 |

Calibration:

Variables derived from this type of data:

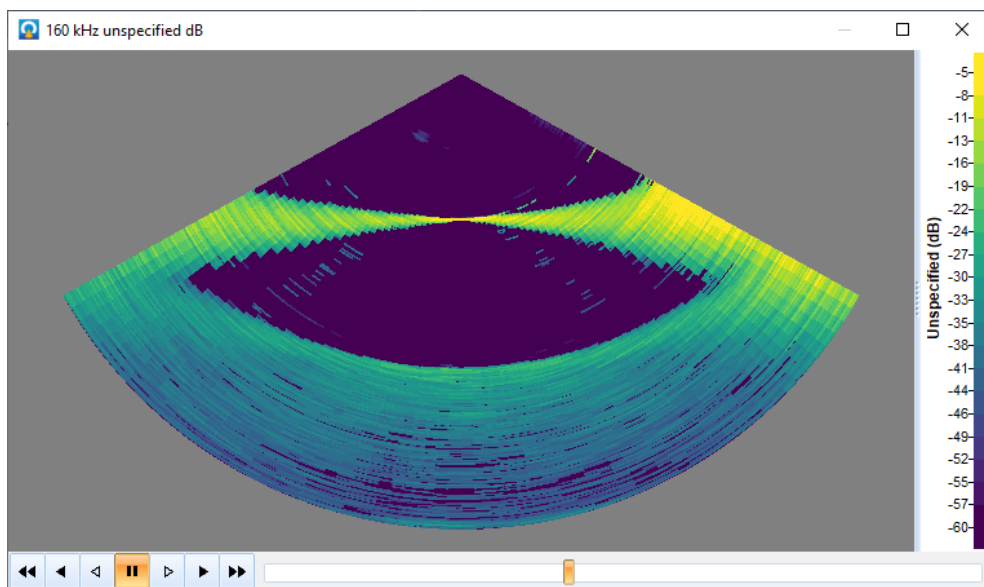
- ☒ unspecified dB pings (160 kHz, 1786 pings)
- ☒ position GPS fixes GPGGA (5636 fixes)
- ☒ heading data GPVTG (1127 measurements)
- ☒ heading data PASHR (11272 measurements)
- ☒ roll data PASHR (11272 measurements)
- ☒ pitch data PASHR (11272 measurements)
- ☒ line data PASHR (11272 segments)

\*.nwsf files are added to Echoview's Filesets window, which lists the information and variables derived from this type of data.

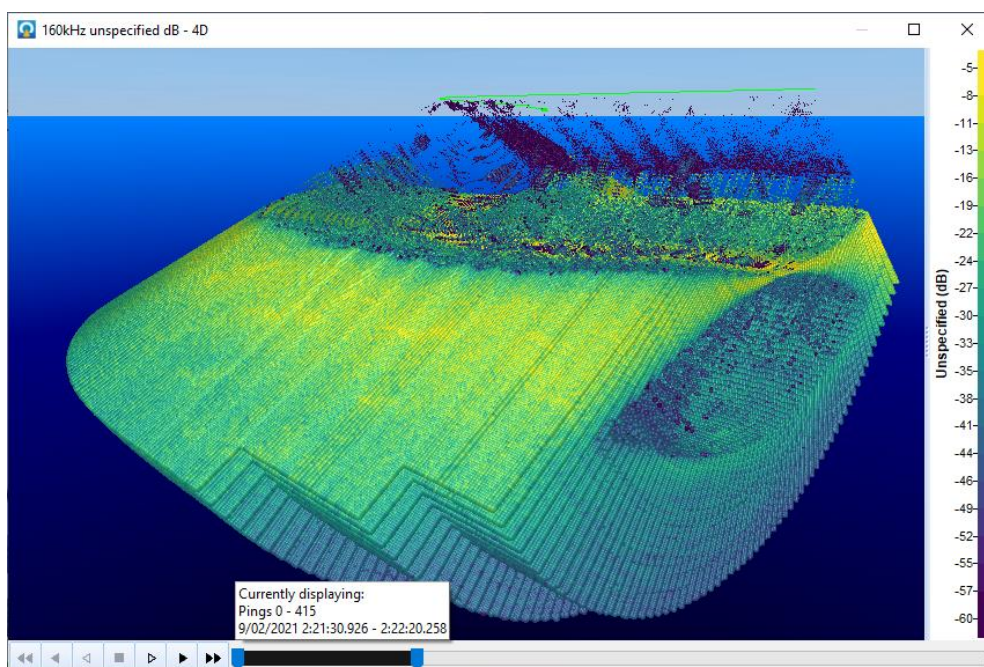
## Echoview capabilities

Echoview provides the following features for WASSP multibeam data processing. Unless otherwise specified in *italics*, the Essentials module is required to use these features.

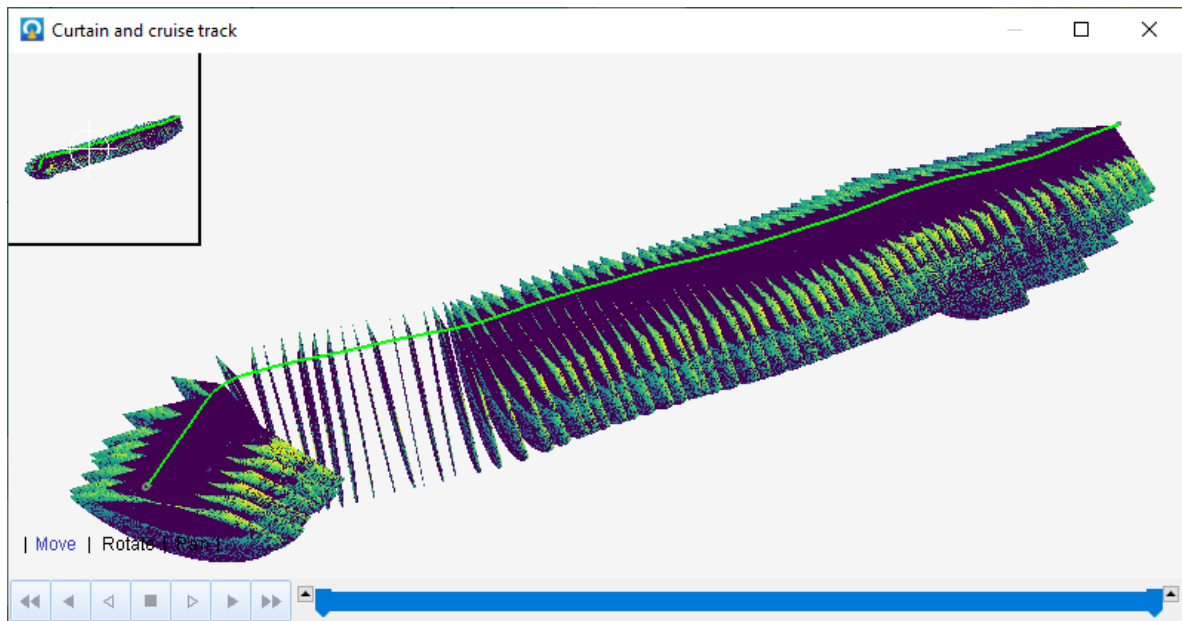
- 1) Visualize and explore ping data:
  - a) As ping-based echograms (with a variety of configurable display tools and options):



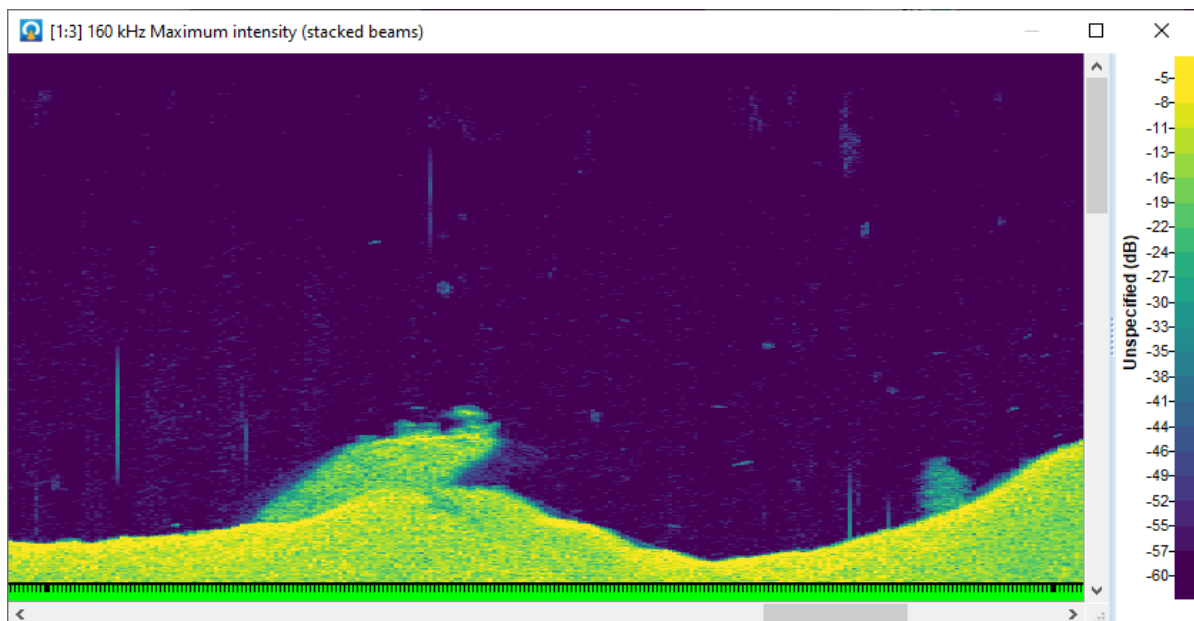
- b) Using the 4D view to view georeferenced samples:



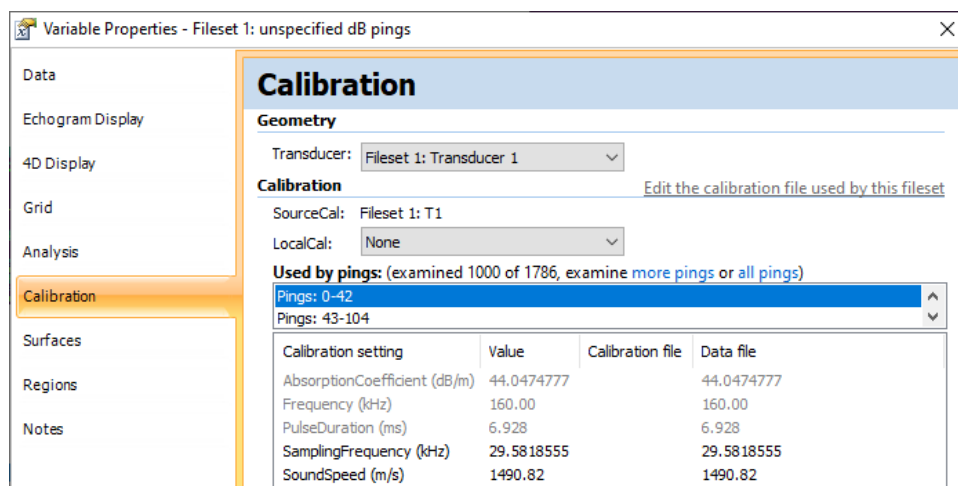
- c) By creating 3D curtains and viewing them in the 3D Scene window:



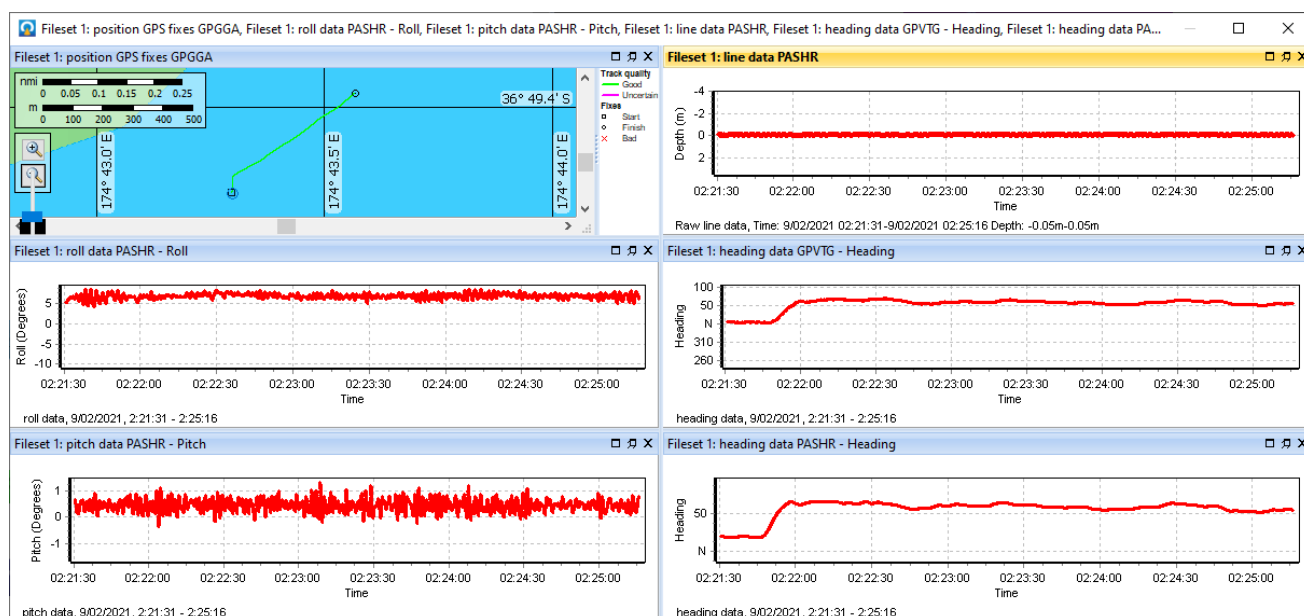
- d) Using the Maximum Intensity operator to view “stacked beams”, where each sample at range  $R$  contains the maximum value of all corresponding multibeam samples that are also at range  $R$ , which gives a helpful overview of data throughout the survey.



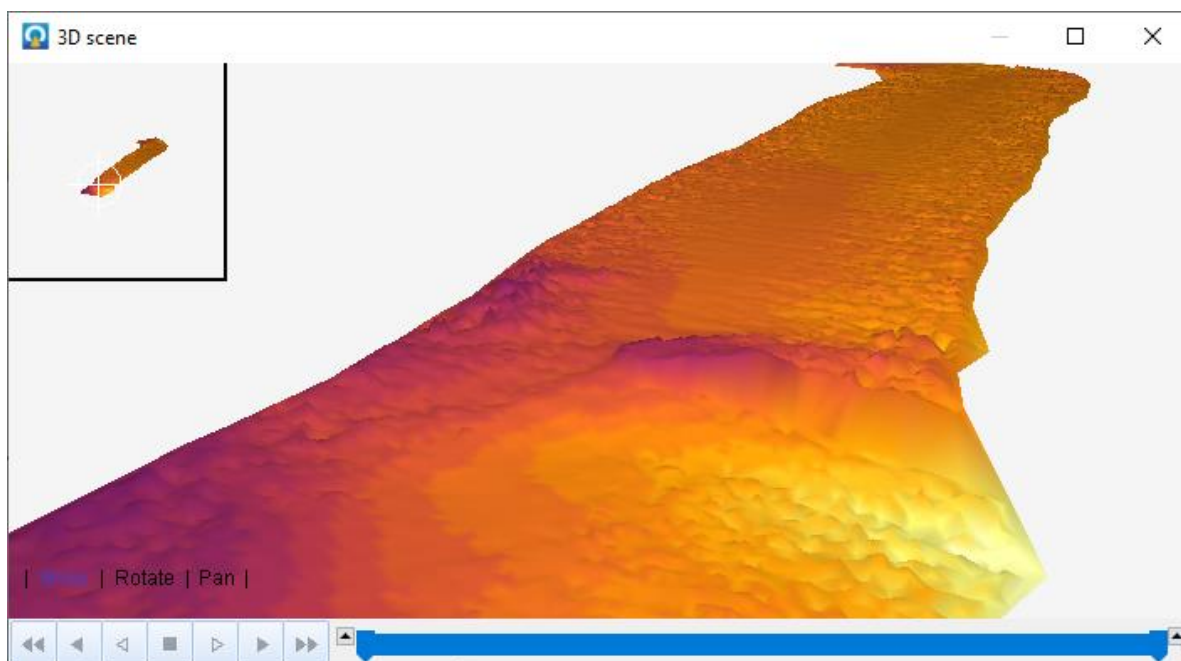
## 2) View and adjust data collection and calibration settings:



## 3) View GPS, heading, pitch, roll, and depth measurements:



- 4) Detect the seafloor or bottom as a surface and then:
  - a) View it as an intersection overlaid on the echogram, and use it to exclude data from further analysis of watercolumn data
  - b) Resample the surface, to smooth the detected bottom
  - c) View the surface in a 3D scene:

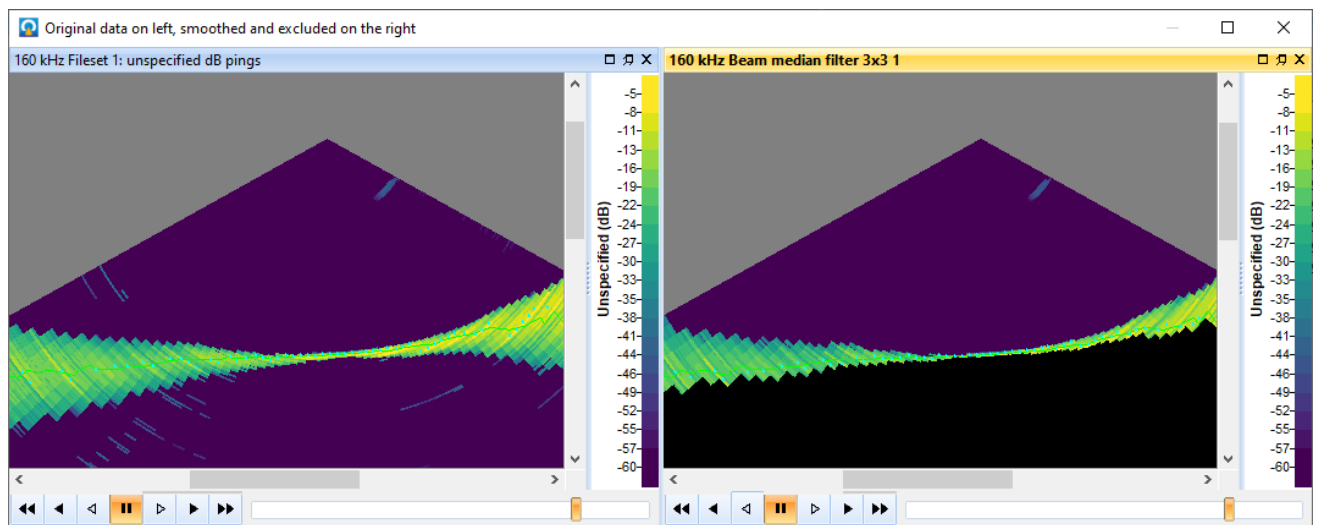


- d) Export depth measurements (XYZ) for use in other software:

|    | A        | B         | C      |
|----|----------|-----------|--------|
| 1  | Latitude | Longitude | Depth  |
| 2  | -36.8231 | 174.7263  | 13.536 |
| 3  | -36.8231 | 174.7262  | 13.465 |
| 4  | -36.8231 | 174.7262  | 13.107 |
| 5  | -36.8231 | 174.7262  | 13.773 |
| 6  | -36.8231 | 174.7262  | 13.362 |
| 7  | -36.8231 | 174.7262  | 13.853 |
| 8  | -36.8231 | 174.7262  | 13.095 |
| 9  | -36.8231 | 174.7262  | 13.189 |
| 10 | -36.8231 | 174.7262  | 13.731 |
| 11 | -36.8231 | 174.7262  | 13.731 |
| 12 | -36.8231 | 174.7262  | 14.004 |
| 13 | -36.8231 | 174.7262  | 13.229 |
| 14 | -36.8231 | 174.7262  | 12.868 |
| 15 | -36.8231 | 174.7262  | 13.085 |



- 5) Smooth data using a 3x3 median filter convolution, e.g., to remove stochastic and other noise effects:

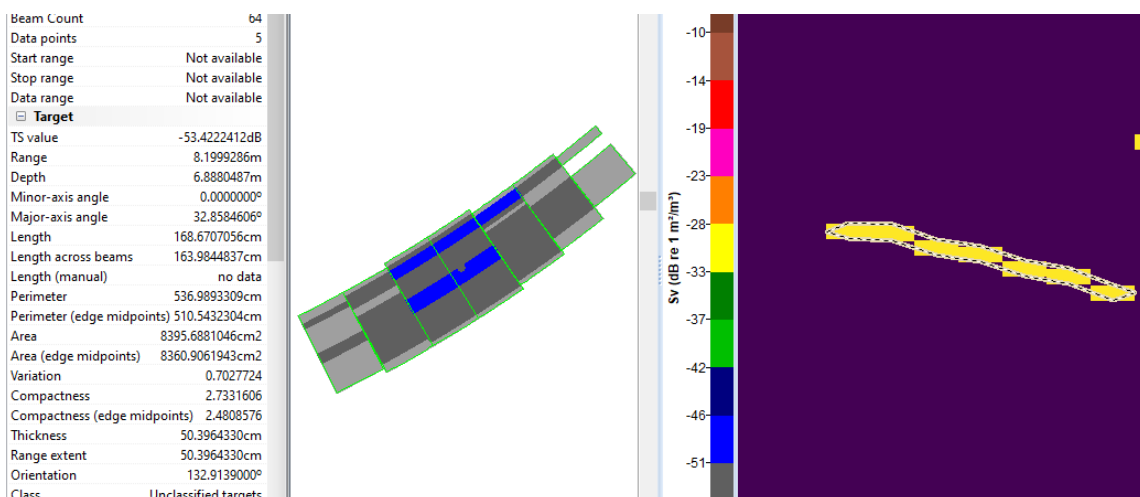


- 6) Perform other data manipulations using virtual variables (*some operators require Advanced Operators*). Examples include:
- Selecting a subset of pings to test algorithms on, before applying to the entire dataset
  - Removing background noise, spikes of impulse noise, suppressing side lobes
  - Applying other convolution algorithms
  - Masking data that pass or fail specific criteria
  - Writing custom sample data manipulation algorithms using a Python-based interface
  - ...and much more - see [this help file page](#) for a comprehensive list
- 7) Export echogram data values to ping-based CSV files, or sample-based georeferenced CSV files:

| Ping_index | Beam_index | Latitude     | Longitude   | Altitude     | Depth        | unspecified dB |
|------------|------------|--------------|-------------|--------------|--------------|----------------|
| 100        | 0          | -36.82560915 | 174.7216209 | 0.033105341  | -0.033105341 | -79.7          |
| 100        | 0          | -36.82560914 | 174.7216206 | 0.019316018  | -0.019316018 | -250.57        |
| 100        | 0          | -36.82560913 | 174.7216204 | 0.005526696  | -0.005526696 | -250.57        |
| 100        | 0          | -36.82560912 | 174.7216201 | -0.008262625 | 0.008262625  | -119.54        |
| 100        | 0          | -36.82560911 | 174.7216198 | -0.022051945 | 0.022051945  | -114.17        |
| 100        | 0          | -36.82560909 | 174.7216196 | -0.035841267 | 0.035841267  | -138.7         |
| 100        | 0          | -36.82560908 | 174.7216193 | -0.049630588 | 0.049630588  | -106.68        |
| 100        | 0          | -36.82560907 | 174.721619  | -0.063419907 | 0.063419907  | -105.46        |
| 100        | 0          | -36.82560906 | 174.7216187 | -0.077209229 | 0.077209229  | -100.4         |
| 100        | 0          | -36.82560905 | 174.7216185 | -0.090998549 | 0.090998549  | -91.64         |
| 100        | 0          | -36.82560903 | 174.7216182 | -0.10478787  | 0.10478787   | -90.42         |
| 100        | 0          | -36.82560902 | 174.7216179 | -0.11857719  | 0.11857719   | -100.78        |

- 8) Detect individual fish, bubbles or other targets using the Multibeam Target Detection operator (*requires Multibeam Fish Tracking*), and then:
- Convert detected targets to a 2D “echogram” which shows targets at the range that they were detected for each ping
  - Filter targets based on properties (e.g., minimum target length)

c) Detect fish tracks from targets



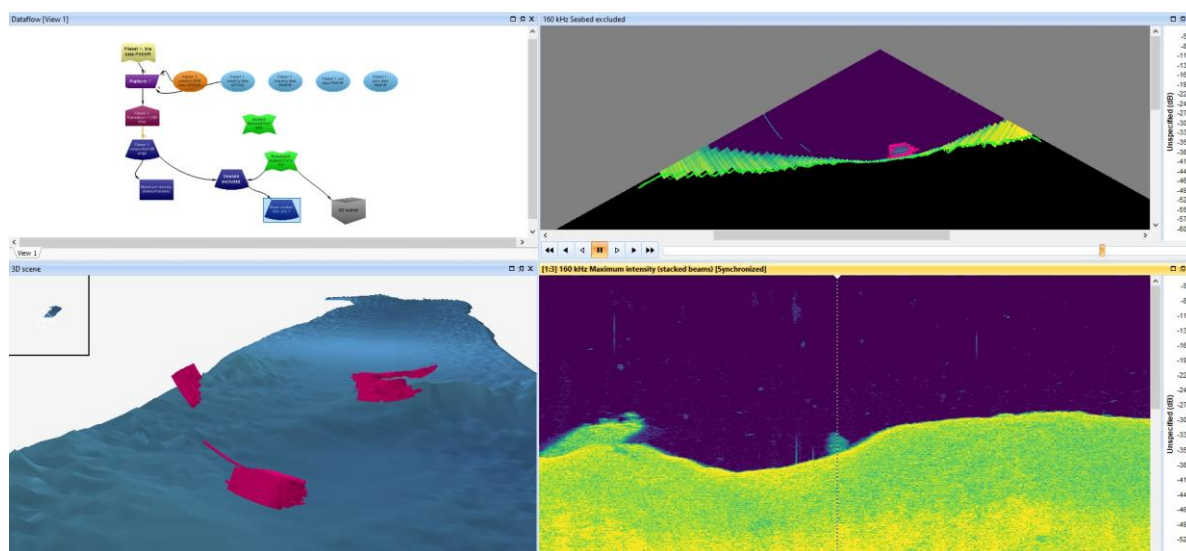
Target properties on left, target on multibeam variable in centre, fish track detected from targets on right.

d) Calculate and export metrics for the targets and tracks:

| Region | IC       | Height_m | Date_M     | Time_M   | Lat_M    | Lon_M | Num_targ | TS_mean  | Target_rai | Speed_4D | Fish_track | Time_in_t | Distance | Thickness |
|--------|----------|----------|------------|----------|----------|-------|----------|----------|------------|----------|------------|-----------|----------|-----------|
| 5      | 0.056806 | 20210209 | 02:21:31.5 | -36.8258 | 174.7216 | 4     | -50.7415 | 11.17702 | 2.3132     | 0.022679 | 0.4131     | 0.9556    | 0.056806 |           |
| 7      | 0.056806 | 20210209 | 02:21:32.1 | -36.8258 | 174.7216 | 4     | -57.3589 | 16.78899 | 41.0472    | 0.041059 | 0.31       | 12.7246   | 0.056806 |           |
| 8      | 0.056806 | 20210209 | 02:21:32.4 | -36.8258 | 174.7216 | 6     | -46.6991 | 15.61764 | 2.7737     | -0.03355 | 0.5166     | 1.4329    | 0.056806 |           |
| 9      | 0.056806 | 20210209 | 02:21:33.7 | -36.8258 | 174.7216 | 3     | -57.5618 | 15.49301 | 2.965      | 0.005322 | 0.2066     | 0.6126    | 0.056806 |           |
| 10     | 0.056806 | 20210209 | 02:21:33.7 | -36.8258 | 174.7216 | 4     | -57.434  | 16.21014 | 3.2882     | -0.04938 | 0.3098     | 1.0187    | 0.056806 |           |
| 11     | 0.056806 | 20210209 | 02:21:33.7 | -36.8258 | 174.7216 | 4     | -56.5798 | 12.44966 | 2.4263     | 0.025189 | 0.3098     | 0.7517    | 0.056806 |           |

9) Detect aggregations of fish, gas plumes, or other targets (*requires Multibeam School Detection*), and then:

a) View detected school intersections on the echogram, and the 3D schools in Scene window:



Detected schools are highlighted in pink

b) Calculate and export metrics for the detected schools:

| Region_class                    | Unclassified regions | Unclassified regions | Unclassified regions | Unclassified regions |
|---------------------------------|----------------------|----------------------|----------------------|----------------------|
| Region_name                     | 3D Region1           | 3D Region2           | 3D Region3           | 3D Region4           |
| Region_id                       | 1                    | 2                    | 3                    | 4                    |
| Vertices                        | 6988                 | 6983                 | 1064                 | 2970                 |
| Triangles                       | 14140                | 14204                | 2128                 | 5992                 |
| Surface_area                    | 309.781              | 336.968              | 34.549               | 172.061              |
| Length_NS                       | 8.17                 | 12.132               | 3.738                | 8.04                 |
| Length_EW                       | 15.122               | 10.002               | 2.293                | 6.2                  |
| Depth_minimum                   | 13.314               | 13.029               | 7.55                 | 12.394               |
| Depth_maximum                   | 16.635               | 16.606               | 11.724               | 17.361               |
| Height                          | 3.32                 | 3.576                | 4.174                | 4.967                |
| Volume                          | 38.446               | 27.336               | 3.182                | 25.147               |
| Geometric_center_latitude       | -36.82369878         | -36.82365664         | -36.82362524         | -36.82350859         |
| Geometric_center_longitude      | 174.7246587          | 174.7248058          | 174.7251787          | 174.7251934          |
| Geometric_center_depth          | 15.013               | 14.296               | 9.329                | 15.734               |
| OBB_length1                     | 15.09                | 12.202               | 3.838                | 9.162                |
| OBB_length2                     | 8.433                | 8.411                | 2.9                  | 5.906                |
| OBB_length3                     | 2.308                | 3.453                | 2.271                | 3.289                |
| OBB_axis1_elevation             | 4.314                | 8.412                | 67.756               | 15.7                 |
| OBB_axis1_azimuth               | 86.004               | 203.426              | 159.941              | 138.517              |
| OBB_axis2_rotation              | 17.255               | 176.727              | 79.992               | 16.055               |
| Intersection_area_first_ping    | 0                    | 0                    | 0                    | 0                    |
| Intersection_area_last_ping     | 0                    | 0                    | 0                    | 0                    |
| Intersection_area_first_beam    | 0                    | 0                    | 0                    | 0                    |
| Intersection_area_last_beam     | 0                    | 0                    | 1.549                | 0                    |
| Intersection_area_maximum_range | 0                    | 0                    | 0                    | 0                    |
| Roughness                       | 8.057                | 12.327               | 10.856               | 6.842                |
| Acquisition_start_date          | 9/02/2021            | 9/02/2021            | 9/02/2021            | 9/02/2021            |
| Acquisition_start_time          | 2:24:11              | 2:24:16              | 2:24:31              | 2:24:33              |

10) Automate data processing using scripts (*requires Automation*), which can save manual data processing time – simply review the results of the above techniques once calculations and detections are completed.

a) See the “Introduction to COM scripting” tutorial [here](#) and example scripts [here](#).

Please contact [support@echoview.com](mailto:support@echoview.com) with any technical questions.

## Echoview licensing

Echoview’s licensing is modular. The specific Echoview modules that a WASSP user needs to purchase will depend on the nature of the data that’s been recorded, and their research goals. Essentials is required, one or both of Multibeam Fish Tracking and Multibeam School Detection are likely, and Advanced Operators and Automation are worth considering.

We’re always happy to review some customer example data to provide more definitive suggestions for both licensing requirements and data processing approaches.

License prices are available from [info@echoview.com](mailto:info@echoview.com), with options including perpetual licenses, annual subscriptions, and short-term leases.





# LIMNOLOGY and OCEANOGRAPHY: METHODS



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## Characterizing the three-dimensional distribution of schooling reef fish with a portable multibeam echosounder

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### Abstract

Multispecies schools of small planktivorous fishes are important constituents of reefs and coastal infrastructure; however, determining the extent and distribution of these schools is challenging. Here, we describe a novel use of a low-cost portable multibeam echosounder from a small vessel, which can concurrently measure detailed bathymetry and the distribution of mid-water targets with high spatial accuracy, regardless of light availability or water clarity. Fish abundance and biomass are not easily quantified by multibeam echosounders, so we developed a new metric for delineating the gridded horizontal distribution of school thickness, and assessed the metric's efficacy by examining its correlation with mean volume backscattering strength derived from a calibrated 38 kHz split-beam echosounder ( $R = 0.67$ ). We measured the distribution of fish school thickness around clusters of large concrete modules of an artificial reef using a multibeam echosounder, complemented with underwater video to aid species identification. The mean distribution of school thickness was mapped around the reef field with generalized additive mixed models. Model spatial predictions indicated schools aggregated around module clusters, rather than individual modules. Dynamic schools of fish in relatively shallow coastal waters ( $\sim 30$  m) can be surveyed over  $400,000 \text{ m}^2$  at  $3 \text{ m s}^{-1}$  in just 60 min. Portable multibeam echosounders are an accessible and valuable addition to quantifying the dynamic distributions of coastal fishes around features with high vertical relief.

<https://aslopubs.onlinelibrary.wiley.com/doi/abs/10.1002/lom3.10427>